

Regional 4DEnVar with global ensemble at NCEP

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GSI Hybrid Variational-Ensemble

Incorporate ensemble perturbations directly into variational cost function through extended control variable Lorenc (2003)

$$J(\mathbf{x}'_f, \boldsymbol{\alpha}) = \beta_f \frac{1}{2} (\mathbf{x}'_f)^T \mathbf{B}^{-1} (\mathbf{x}'_f) + \beta_e \frac{1}{2} \sum_{n=1}^N (\boldsymbol{\alpha}^n)^T \mathbf{L}^{-1} (\boldsymbol{\alpha}^n) + \frac{1}{2} \sum_{t=1}^T (\mathbf{y}'_t - \mathbf{H} \mathbf{x}'_t)^T \mathbf{R}^{-1} (\mathbf{y}'_t - \mathbf{H} \mathbf{x}'_t)$$

$$\mathbf{x}'_t = \mathbf{x}'_f + \sum_{n=1}^N \boldsymbol{\alpha}^n \circ \mathbf{x}'_{et} \quad \frac{1}{\beta_f} + \frac{1}{\beta_e} = 1$$

$\mathbf{x}'_f$ is the increment associated with the static covariance

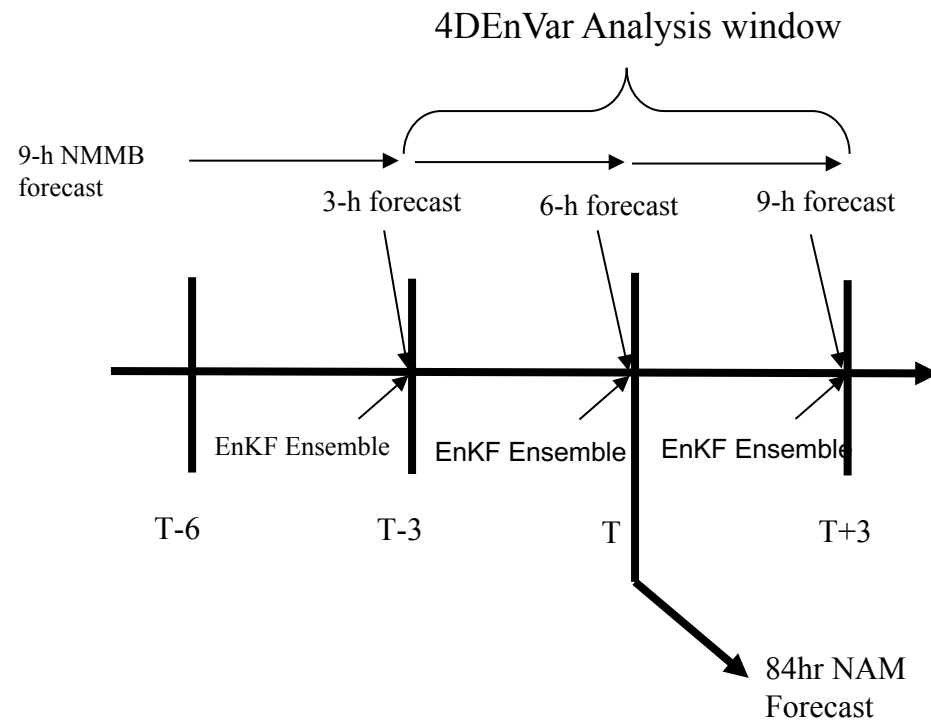
β_f & β_e : weighting coefficients for fixed and ensemble covariance respectively

$\mathbf{x}'_t$: (total increment) sum of $\mathbf{x}'_f$ increment from fixed/static $\mathbf{B}$ ($\mathbf{x}_f$) and ensemble $\mathbf{B}$

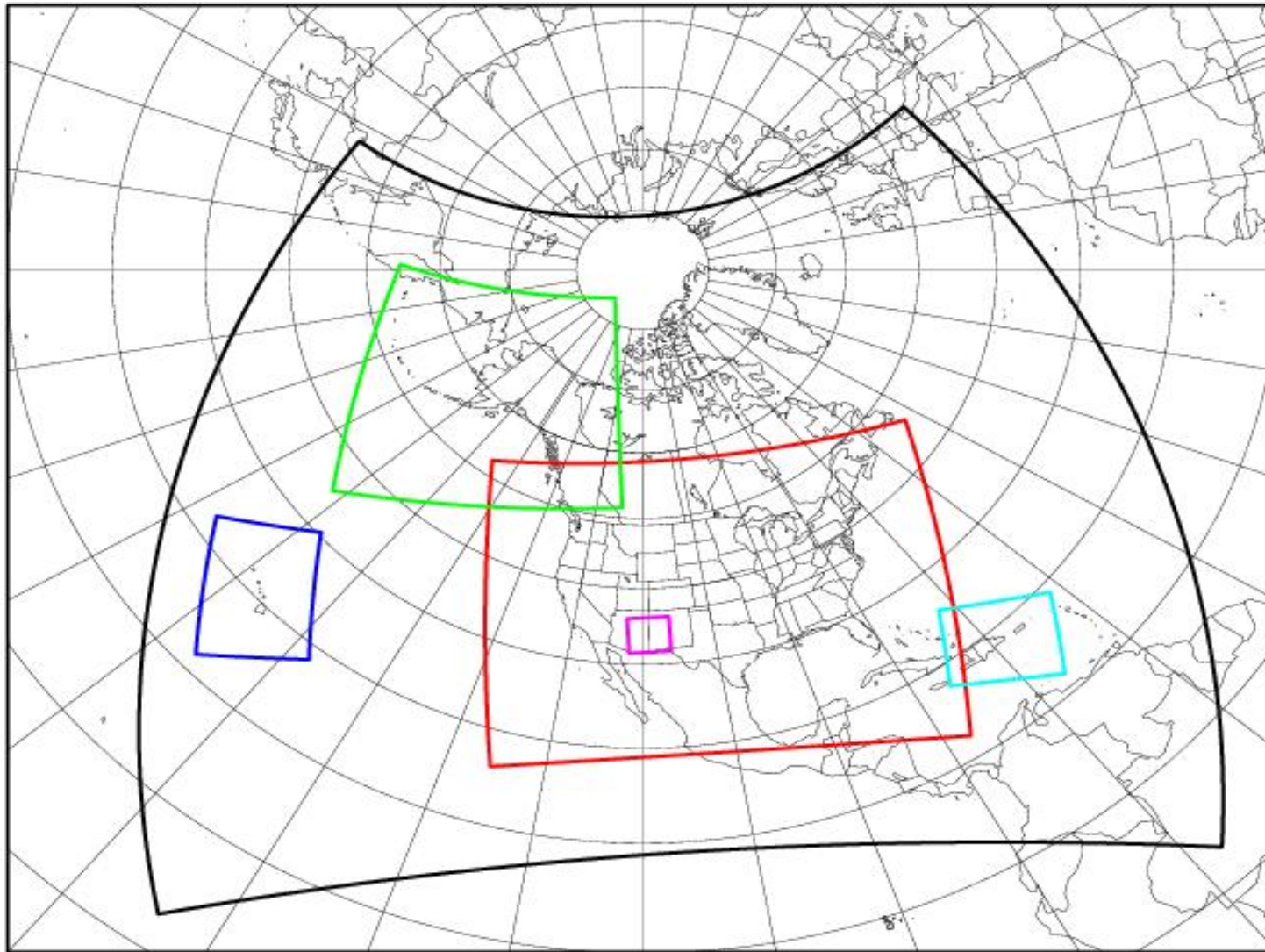
α_k : extended control variable; $\mathbf{x}'_{et}$: ensemble perturbation

$\mathbf{L}$: correlation matrix (localization on ensemble perturbations)

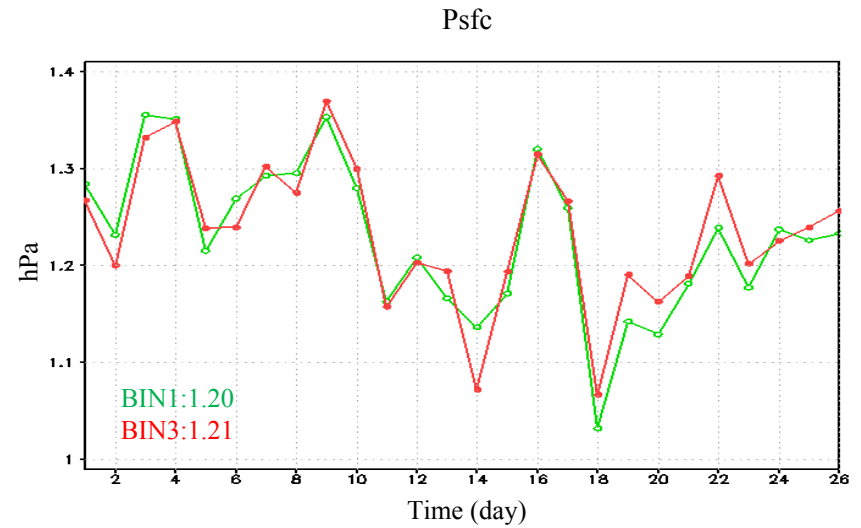
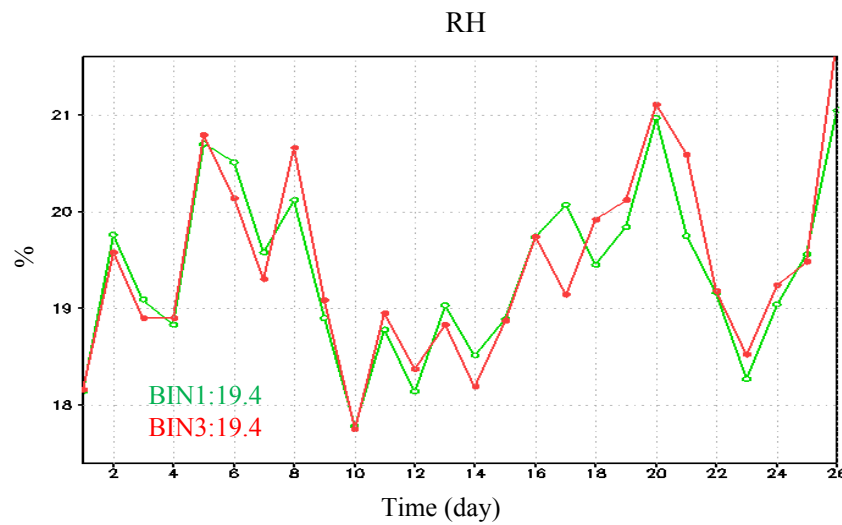
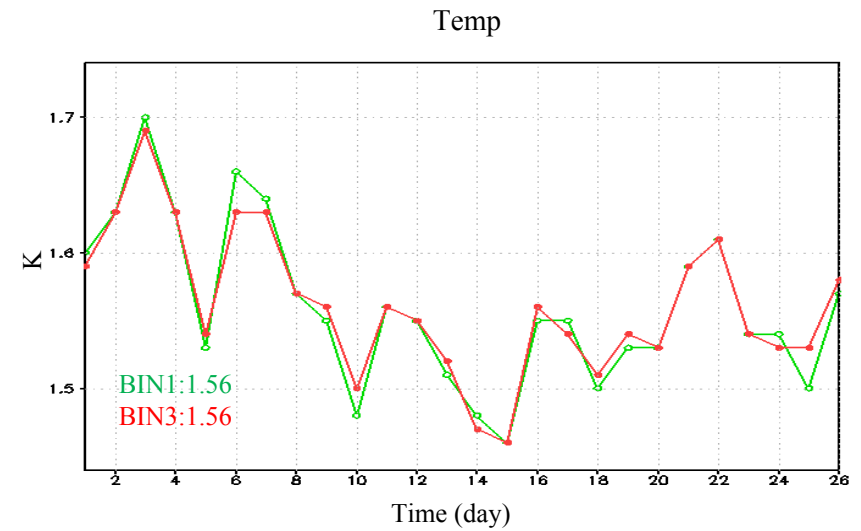
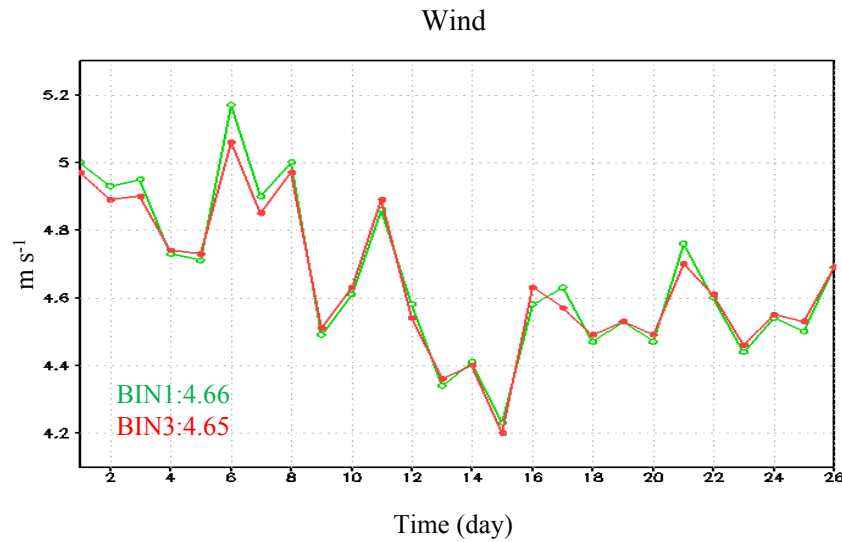
NDAS 4D_{En}Var



NAM integration domain



Sensitivity of hourly and 3-hourly bins



Impact of time bin

- less interpolation error with smaller time bin; more computational costs
- with 4DVar where all observations used when integrating the TL model
- with 4DEnVar best ensemble member identified with the observations in each bin
data density may be a problem when bin width become small.
(extreme example: 1 observation in the bin, similar weight to all members)

4DEnVar & TC

EnVar: use only ensemble perturbations

ensemble mean disregarded

Goal: initiate from the best of the 2 systems according to fit to observations

Option: **Trajectory Correction**

add an option to correct model/mean trajectories.

at each time bin, add 1 extra ensemble member to existing 80:

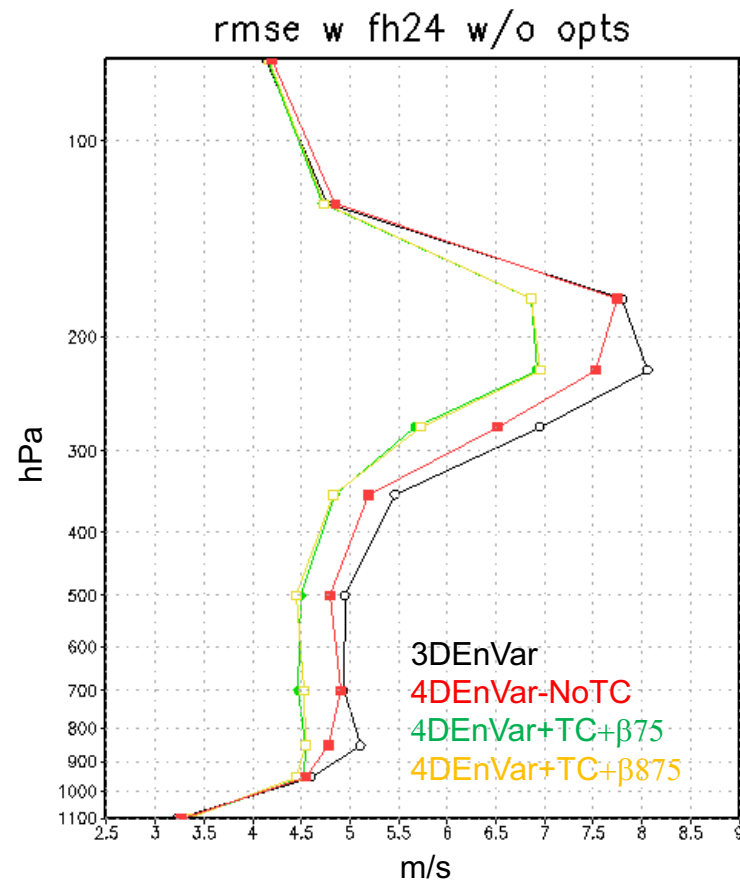
differences of the global ensemble mean(En_m) and the regional first guess (X_g)

$$\text{from } \mathbf{x}'_t = \mathbf{x}'_f + \sum_{n=1}^N \boldsymbol{\alpha}^n \circ \mathbf{x}'_{et}{}^n$$

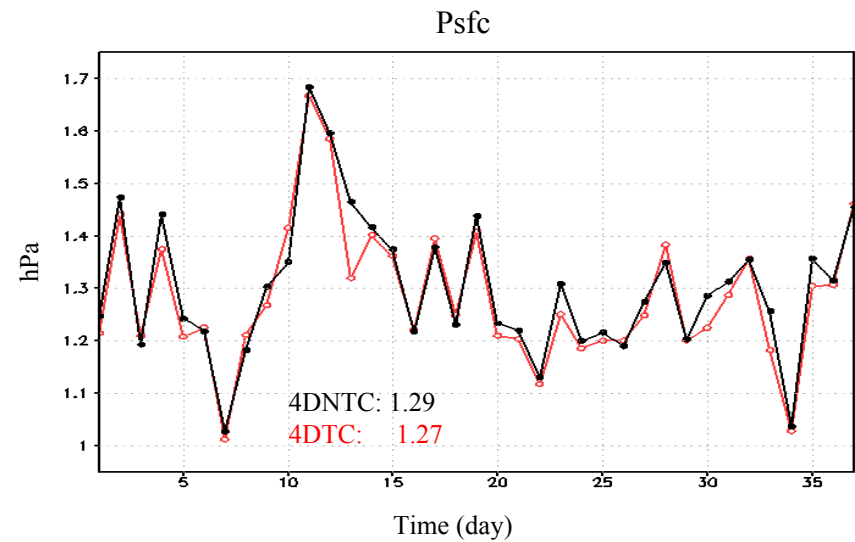
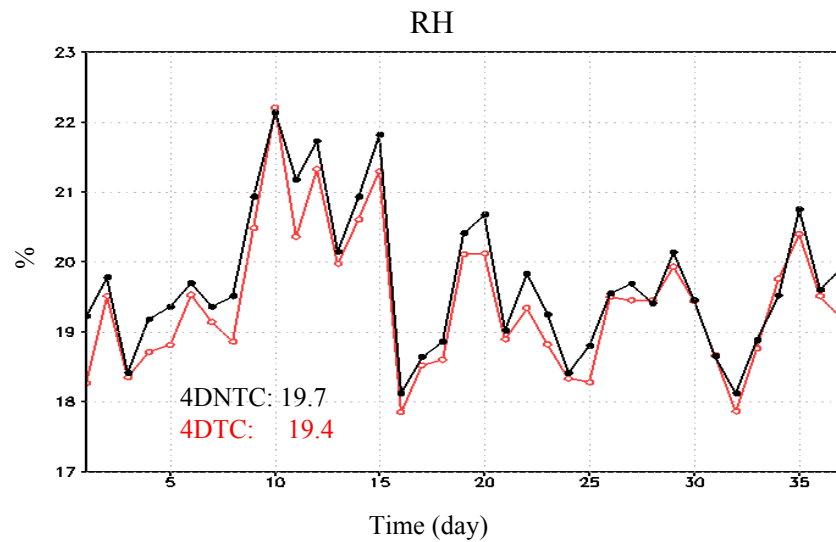
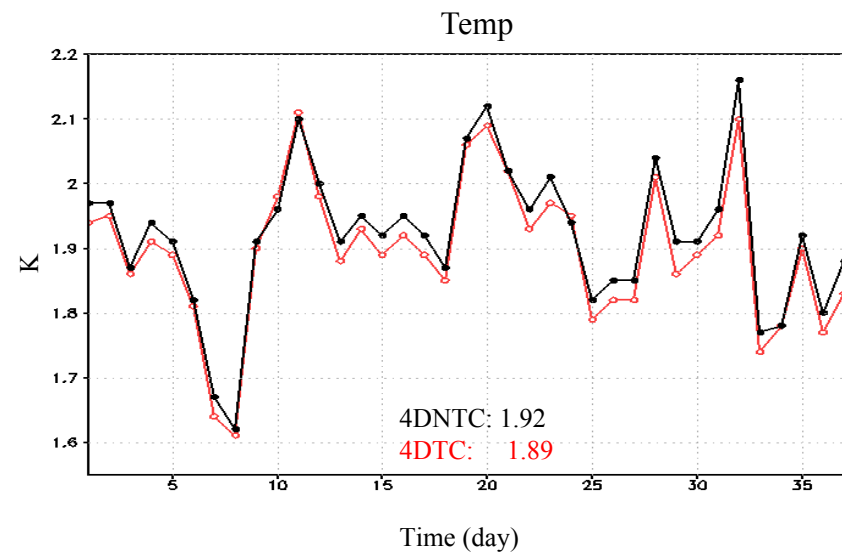
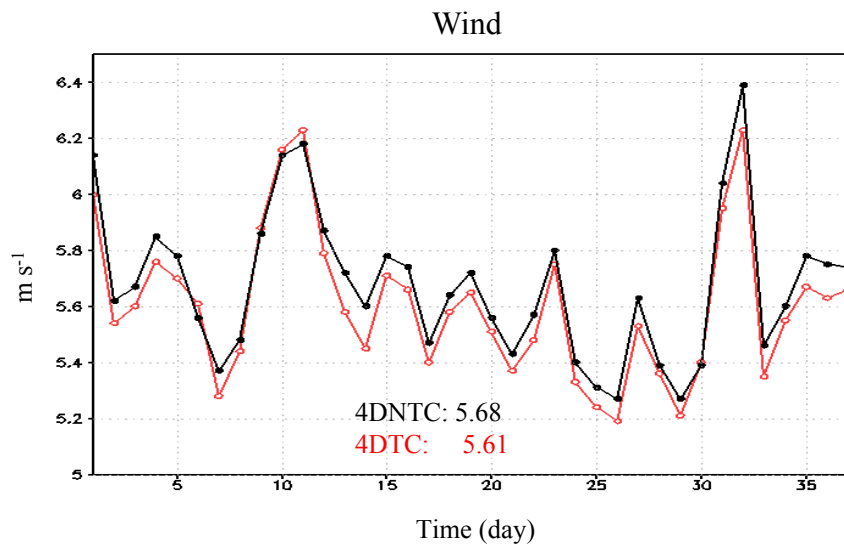
$$X_a = X_g + \alpha (En_m - X_g) + \dots \rightarrow En_m$$

ability to locally bias correct first guess trajectory toward ensemble mean.

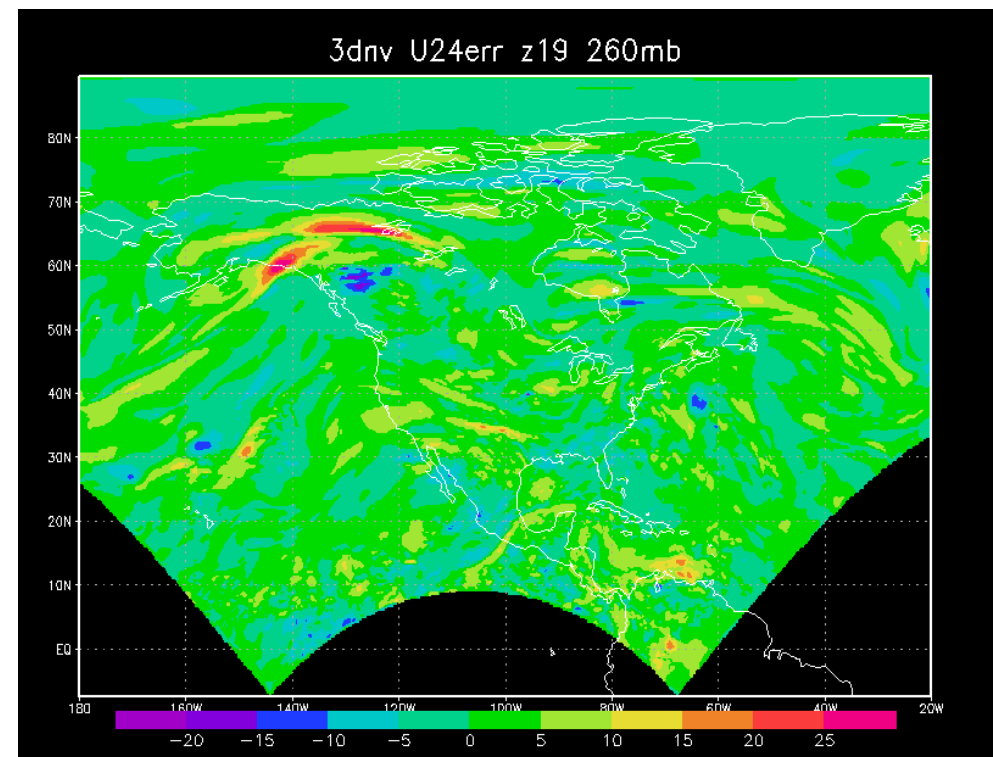
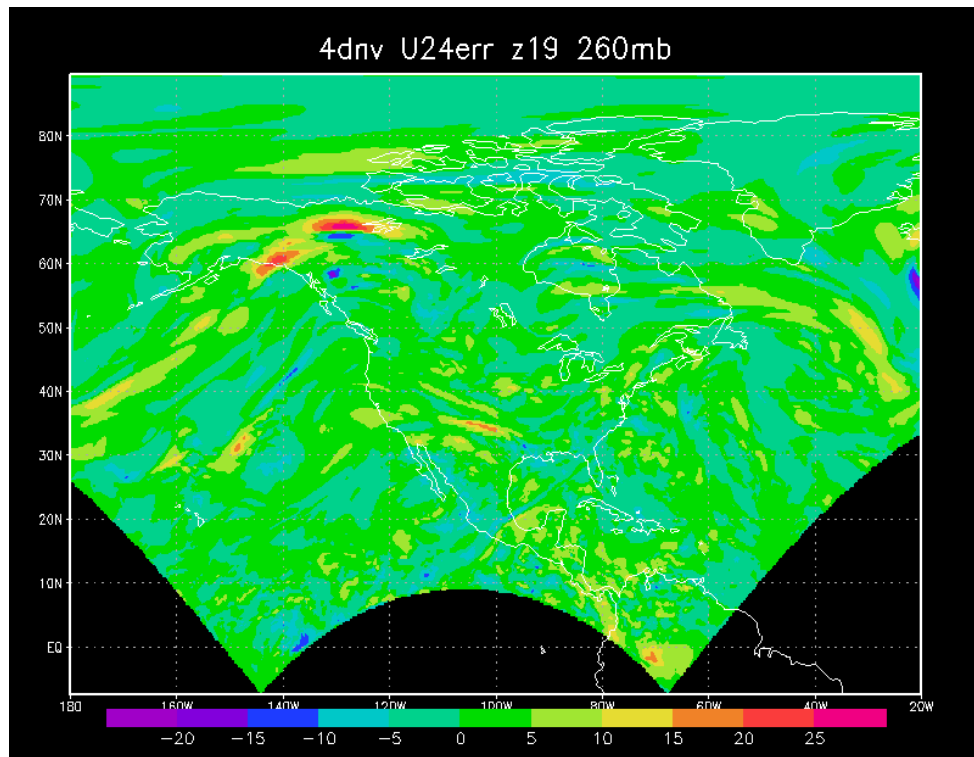
4DEnVar: Magnitude of impact from trajectory correction



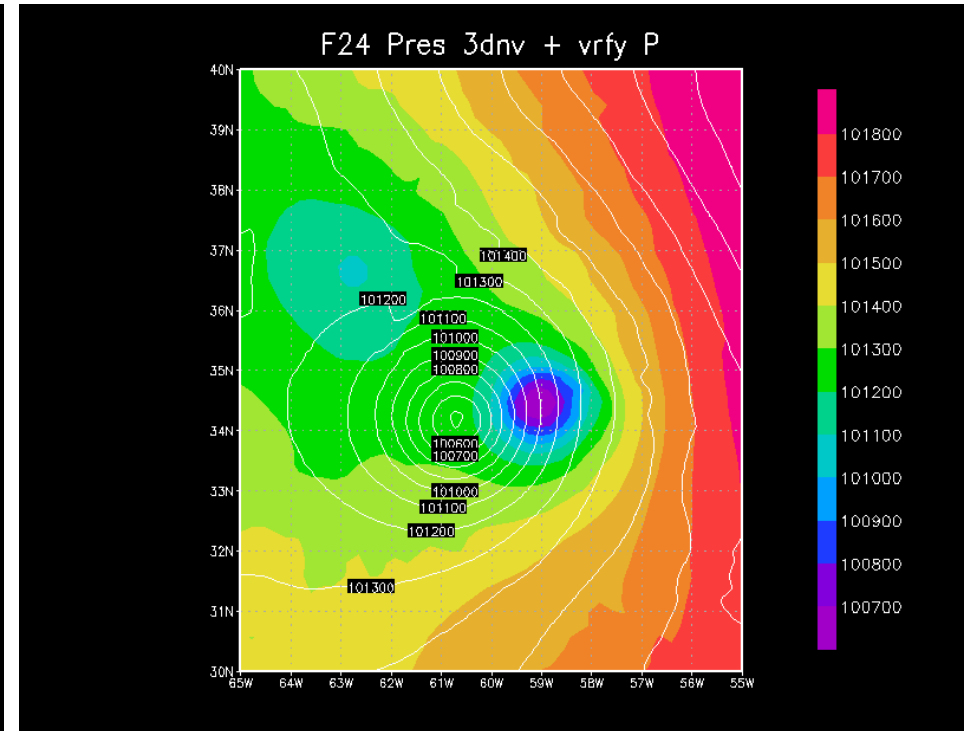
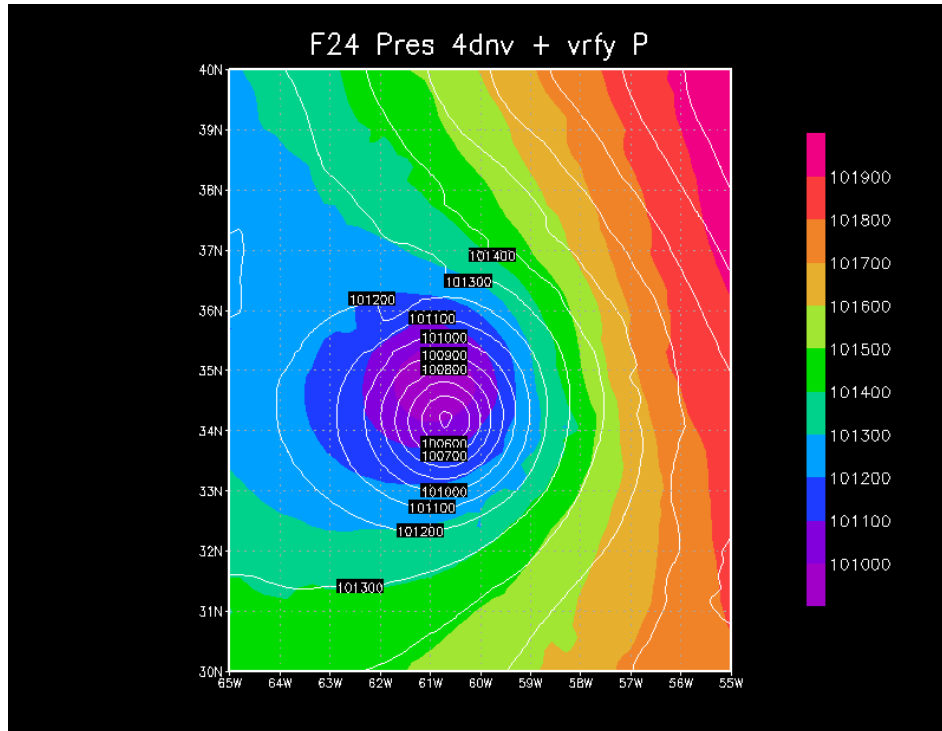
Impact of Trajectory Correction



3D/4D EnVar u24err 260mb



3D/4DEnVar F24 P error tropical cyclone



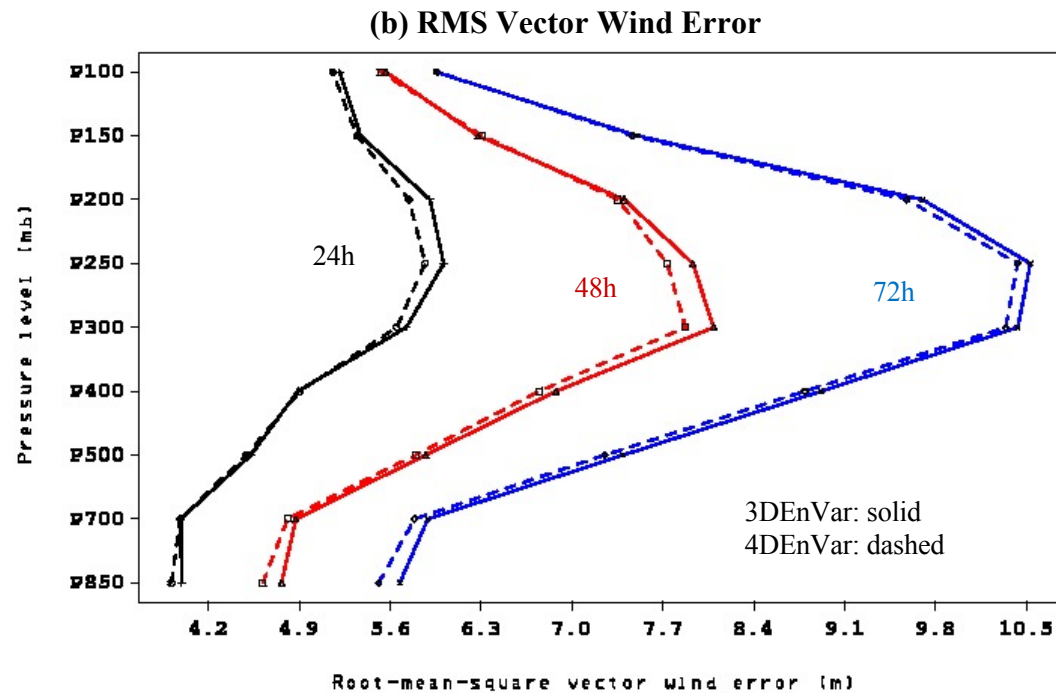
F24 with 4DEnVar smaller position and size error

Testing 4DEnVar in NDAS parallel

Results from NDAS parallel by

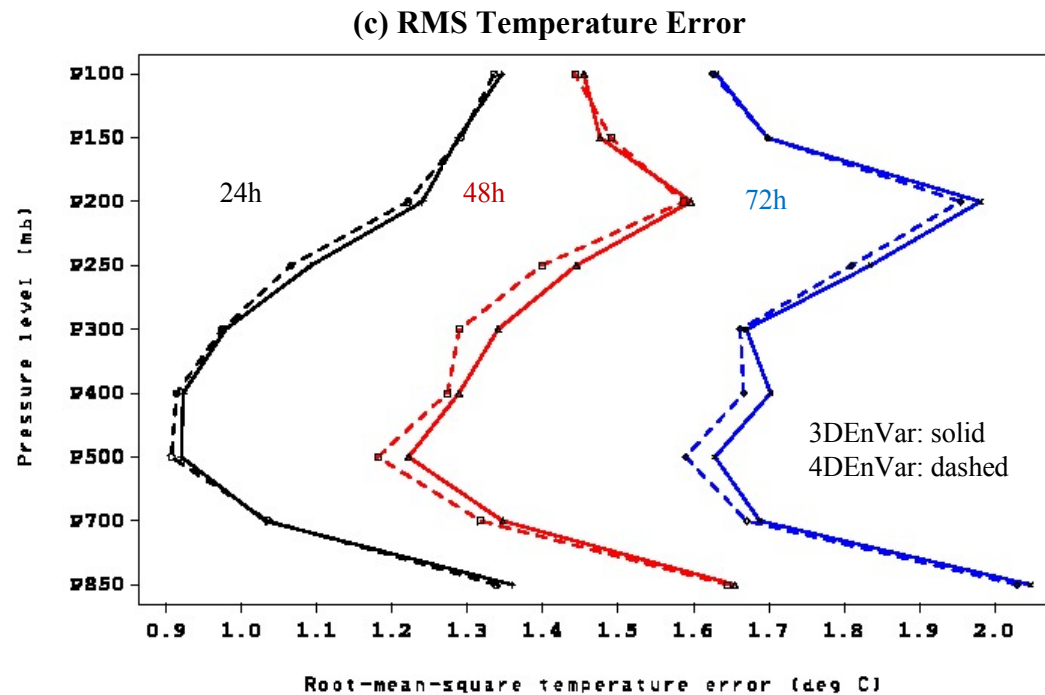
- 1) Eric Rogers: upper air statistics
- 2) Ying Lin: precipitation scores
- 3) Quang Ping Lou: Hurricane tracks

NDAS parallel results



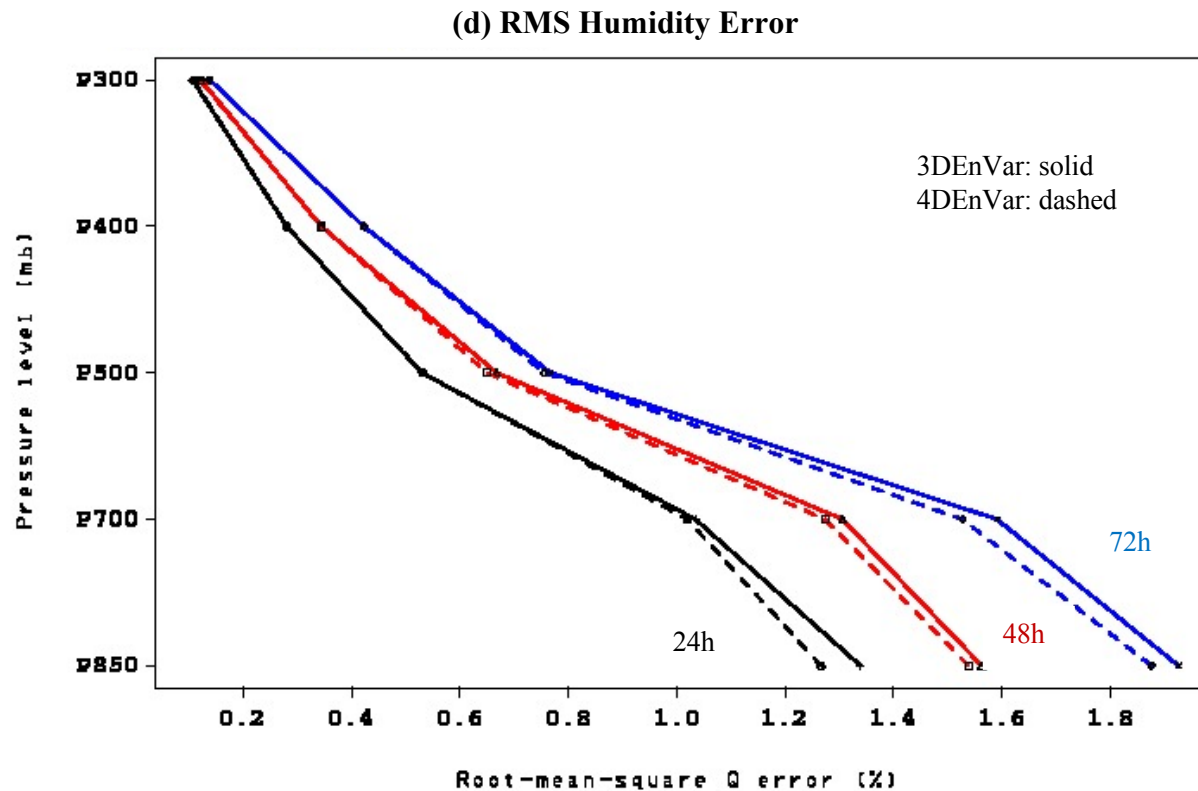
Cumulative RMSE over the continental US for 15 September 2015 to 15 November 2015.
(Eric Rogers EMC)

NDAS parallel results



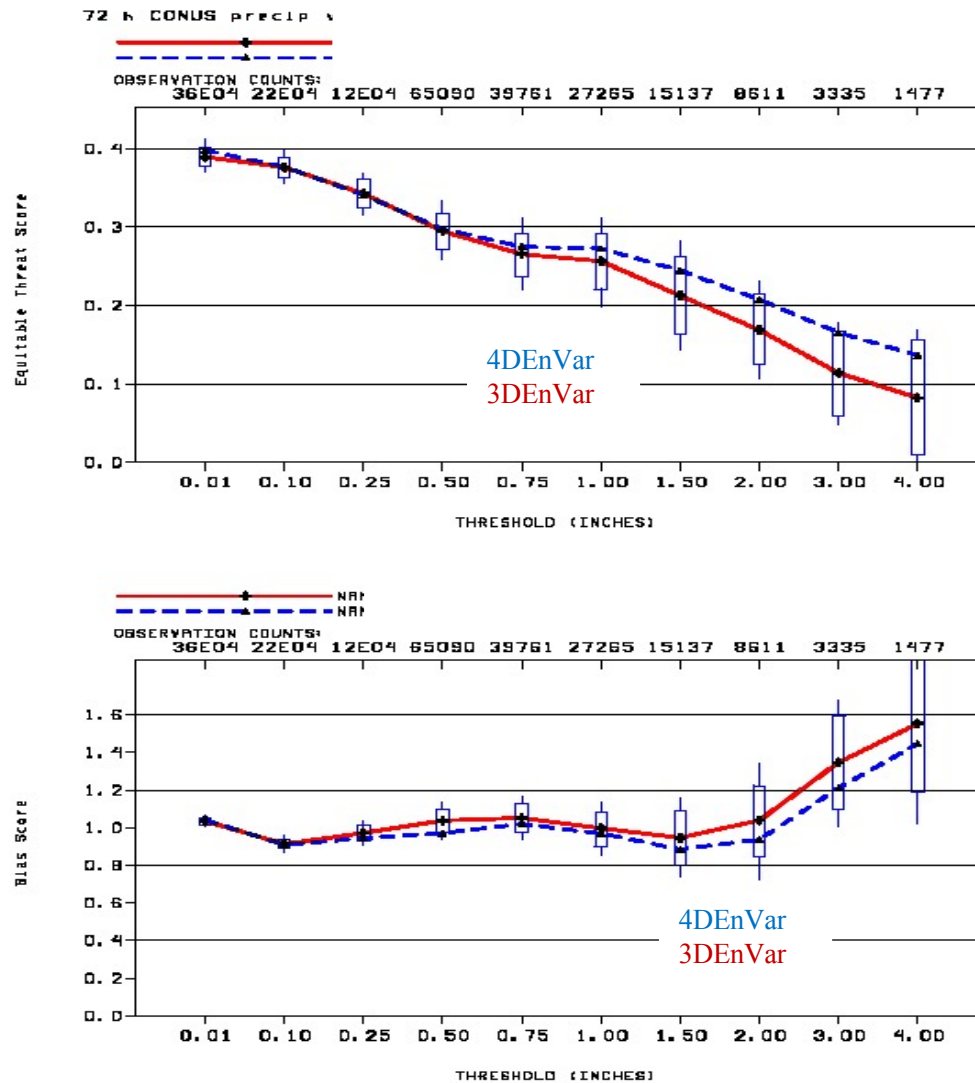
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NDAS parallel results

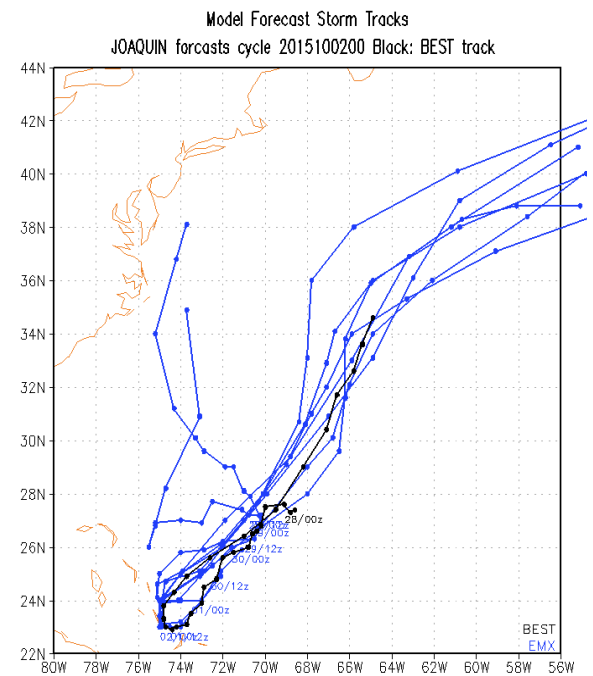
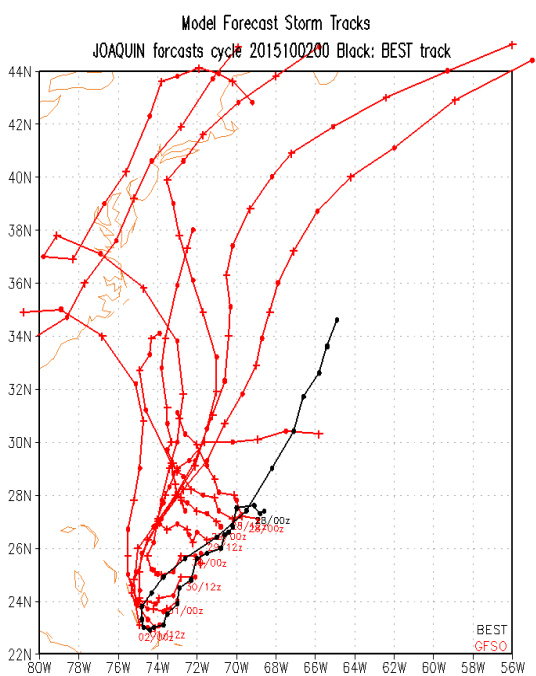
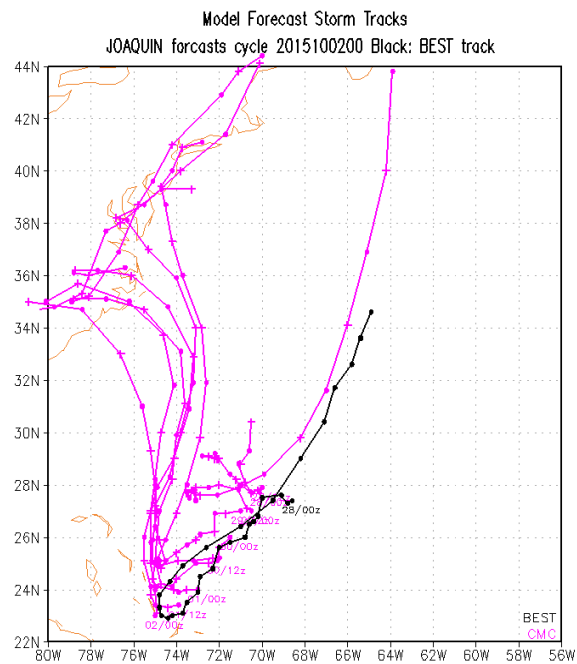
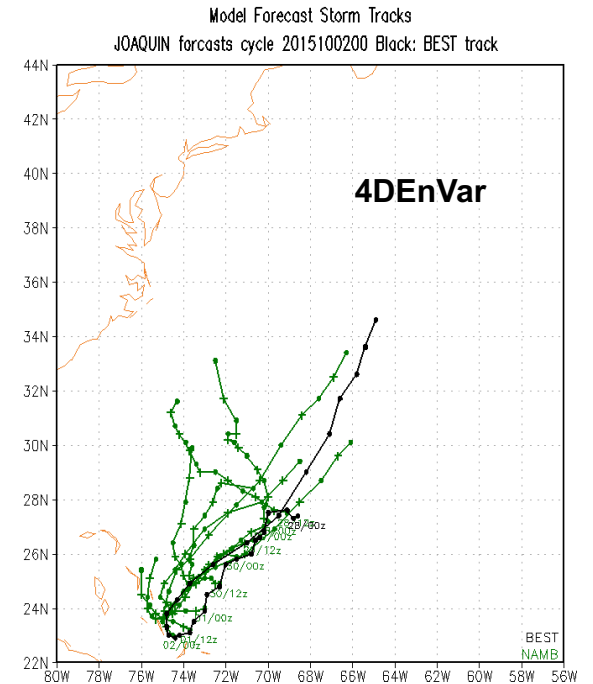
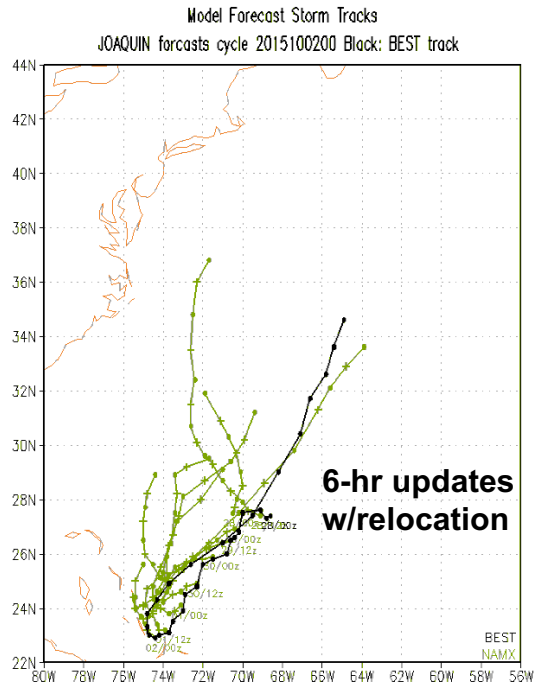
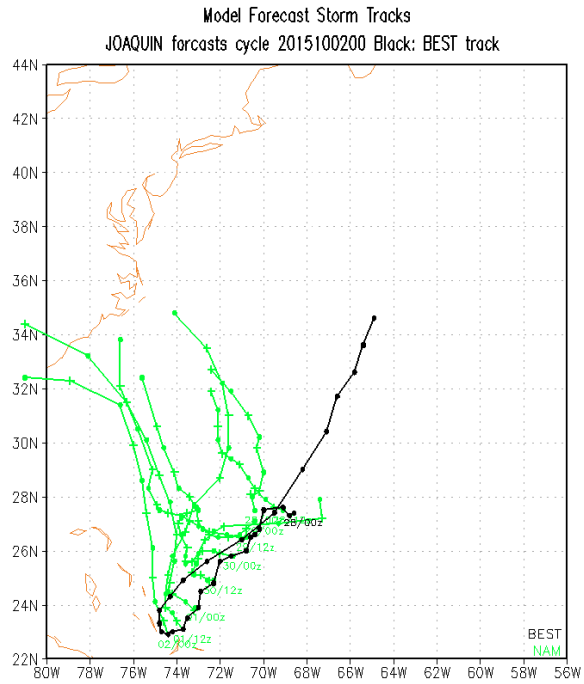


Cumulative RMSE over the continental US for 15 September 2015 to 15 November 2015.
(Eric Rogers EMC)

12-36hr forecasts ETS/bias



Equitable threat scores and bias scores over the continental US for 15 September 2015 to 15 November 2015. (Ying Lin EMC)



00Z 20150928 – 00Z 20151002 (Quang Ping Lou, EMC)

conclusions

- Global ensemble used in regional 4DEnVar with trajectory correction
- TC enriches the ensemble by improving the coverage in phase space
- TC allows the ensemble mean to be used in the analysis with EnVar
- Positive impact from 4DEnVar; advantages on
 - atmospheric statistics
 - precipitation scores
 - hurricane track prediction

extension of the work

- Apply EnVar with TC to combine a super ensemble
- Add regional ensemble (and its mean) beside global ensemble to help define the smaller-scale part of the background error covariance.